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1A01-1	Signal Processing (1)	642	Online Estimation of Complexity Using Variable Forgetting Factor	Koichi Sugisaki (Keio univ.), Hiromitsu Ohmori (Keio univ.)
1A01-2	Signal Processing (1)	553	Study on a Method of Generating a 3D Virtual Foot Model with Use of a Measuring Technique Based on Multiple Camera Image Data	Satoshi Kondo (Tokyo Univ. of Agriculture and Tech), Yasuhiro Akagi (Tokyo Univ. of Agriculture and Tech), Katsuhiro Kitajima (Tokyo Univ. of Agriculture and Tech)
1A01-3	Signal Processing (1)	650	Detection of Bearing Fault Using Hybrid Digital Filter	Shao Yimin (Chongqing Univ.), Hu Yumei (Chongqing Univ.), Wang Shemin (Chongqing Univ.), Zhou Xiaojun (Chongqing Univ.)
1A01-4	Signal Processing (1)	135	An Efficient DC-Notch FIR Filter Design	Kyoung Jae Kim (Hanyang Univ.), Sang Won Nam (Hanyang Univ.)
1A01-5	Signal Processing (1)	411	A New Efficient Matrix Spectral Factorization Algorithm	Lasha Ephremidze (Tokai Univ.), Gigla Janashia (Razmadze Mathematical Institute), Edem Lagvilava (Razmadze Mathematical Institute)
1A02-1	OS: Recent Advances in Mechanical Metrology (1)	56	Uncertainty Evaluation on the Fully-automated Sub-multiple Calibration in the Milligram Range	Masaaki Ueki (NMIJ), Kazunaga Ueda (NMIJ)
1A02-2	OS: Recent Advances in Mechanical Metrology (1)	473	High Accurate Creep Compensation Method for Load Cell	Makoto Makabe (Yamato Scale company), Toru Kohashi (Yamato Scale company)
1A02-3	OS: Recent Advances in Mechanical Metrology (1)	475	Frequency Analysis Method using the Adaptive Algorithm and Application to Dynamic Measurement of Mass and Weight	Yuuki Sasamoto (Osaka Prefectural College of Technology), Toshitaka Umemoto (Osaka Prefectural College of Technology), Motoyuki Adachi (Yamato Scale Co Ltd), Yoichiro Kagawa (Yamato Scale Co Ltd)
1A02-4	OS: Recent Advances in Mechanical Metrology (1)	10	Improved Working Efficiency of Force Standard Machine by Separating Alternative Weight Stacks	Toshiyuki Hayashi (AIST), Yoshihisa Katase (AIST), Hiroshi Maejima (AIST), Yukio Yamaguchi (AIST), Kazunaga Ueda (AIST), Yoshiyuki Hikichi (Chihodaseiko)
1A03-1	Identification and Estimation	578	Low-Cost Tachometer based on the Recursive Frequency Estimation for Automotive Applications	Ga Hyung choi (Yonsei Univ.), Won Sang Ra (Yonsei Univ.), Tae Sung Yoon (Changwon National Univ.), Jin Bae Park (Yonsei Univ.)
1A03-2	Identification and Estimation	1	Tracking Errors in the Steady State for a 3 Dimensional Tracking Using a Linear Filter	Yoshio Kosuge (Nagasaki Univ.)
1A03-3	Identification and Estimation	358	Some Extensions of the Monotonic Signal Estimation Method	Osamu Kobayashi (Yamaguchi Univ.), Yuji Wakasa (Yamaguchi Univ.), Kanya Tanaka (Yamaguchi Univ.), Takuya Akashi (Yamaguchi Univ.)
1A03-4	Identification and Estimation	14	Orientation Estimation by Error-State Extended Kalman Filter in Quaternion Vector Space	Mohammad Ahmadi (Shiraz Univ.), Alireza Khayatian (Shiraz Univ.), Paknush Karimaghaee (Shiraz Univ.)
1A03-5	Identification and Estimation	259	Development of Recognition System for Billet Identification	Changhyun Park (Pohang Univ.), SangCheul Won (Pohang Univ.)
1A03-6	Identification and Estimation	49	A New Approach for Harmonics Current Extraction For Nonlinear Loads	Aziza M. Zaki (ERI), Ahmed A. Mansour (ERI), Osama A. Mahgoub (Cairo Univ.), Essam E. Abu-ElZahab (Cairo Univ.)
1A05-1	Mechanical Systems Control (1)	51	Compound Passive Filter to Minimize Torque Ripples and EMI Noises in PMSM Drives	Kayhan Gulez (Yildiz Technical Univ.), Ali Ahmed Adam (Yildiz Technical Univ.)
1A05-2	Mechanical Systems Control (1)	570	Biped Walking Robot Using a Stick on Uneven Ground	Hideto Shimizu (Tokyo Denki Univ.), Yuki Wakazuki (Tokyo Denki Univ.), Yaodong Pan (Tokyo Denki Univ.), Katsuhisa Furuta (Tokyo Denki Univ.)
1A05-3	Mechanical Systems Control (1)	165	Damping Path Design of Liquid Container Transfer including Multiple Curve Sections	Yu Yoshida (GS of Shimane Univ.), Masafumi Hamaguchi (Shimane Univ.), Takao Taniguchi (Shimane Univ.)
1A05-4	Mechanical Systems Control (1)	236	Remote Bilateral Control of Master-slave Manipulators with an Environment Observer	Yuki Kakizoe (NAIST), Hisakazu Nakamura (NAIST), Hirokazu Nishitani (NAIST)
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1A06-2	Nonlinear Control (1)	295	Simultaneous Swinging-Up and Stabilization of Double Furuta Pendulums	Noriko Matsuda (Tokyo Denki Univ.), Masaki Izutsu (Tokyo Denki Univ.), Katsuhisa Furuta (Tokyo Denki Univ.)
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1A07-3	OS: Inverse Problems	250	The Method of High-Accuracy 3D Reconstruction for Oblique X-ray CT Images	Satoshi Yoshizawa (Keio Univ.), Toshiyuki Tanaka (Keio Univ.)
1A07-4	OS: Inverse Problems	421	On Distance Measurement Using Band-limited Noise	Noboru Nakasako (Kinki Univ.), Tetsuji Uejo (Kinki Univ.), Norimitsu Ohmata (Kinki Univ.), Atsushi Mori (Kinki Univ.)
1A07-5	OS: Inverse Problems	461	Acoustical Blind Source Separation based on Linear Advection Equation	Kenbu Teramoto (Saga Univ.), MD Tauhidul Islam Khan (Saga Univ.), Akito Uekihara (Saga Univ.)
1A08-1	Intelligent Control (1)	160	Double-Deck Elevator Systems using Genetic Network Programming based on Variance Information	Jin Zhou (Waseda Univ.), Lu Yu (Waseda Univ.), Shingo Mabu (Waseda Univ.), Kotaro Hirasawa (Waseda Univ.), Jinglu Hu (Waseda Univ.), Sandor Markon (FUJITEC Co.Ltd.)
1A08-2	Intelligent Control (1)	580	Acquisition of Fixed Wide View Field of a Biped Robot during a Walking Motion	Kousuke Yoshimi (Tohoku Univ.), Shun Ushida (Tohoku Univ.), Koichiro Deguchi (Tohoku Univ.)
1A08-3	Intelligent Control (1)	48	Adaptive Neural Network Based Controller for Direct Torque Control of PMSM with Minimum Torque Ripples	Kayhan Gulez (Yildiz Technical Univ.), Ali Ahmed Adam (Yildiz Technical Univ.)
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1A09-2	OS: Emerging Control Technologies	28	Transmission of Control Signal in Ocean Environment based on Adaptive Time-Reversal Processing	Jea Soo Kim (Korea Maritime Univ.), Jae Weon Choi (Pusan National Univ.), Y.S. Suh (Ulsan Univ.), Y.H. Byun (Korea Maritime Univ.), J.H. Cho (Korea Maritime Univ.)
1A09-3	OS: Emerging Control Technologies	29	Design of Disturbance Observer for Non-minimum Phase Systems Using PID Controllers	Young-Ik Son (Myongji Univ.), Hyungbo Shim (Seoul National Univ.), Nam H. Jo (Soongsil Univ.), Sung-Jong Kim (Myongji Univ.)
1A09-4	OS: Emerging Control Technologies	30	A Haptic Interface Using a Force-Feedback Joystick	Ae-Kyoung Ko (Pusan National Univ.), Joon-Young Choi (Pusan National Univ.)
1A09-5	OS: Emerging Control Technologies	31	Hierarchical Position Control of Expedition Robots	Duksun Shim (Chung-Ang Univ.), Cheolkwan Yang (Yuhan College), Jinwoo Park (Chung-Ang Univ.), Samuel Chang (Chung-Ang Univ.)
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1A10-3	OS: Frontline of BIX (BioInformation eXchange) Research	648	Image Monitoring of Paddy Field using BIX Image Broker System	Yoshitaka Motonaga (Niigata Univ.), Nobukazu Iguchi (Kinki Univ.), Norikuni Ohtake (Niigata Univ.), Takaharu Kameoka (Mie Univ.)
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1A11-4	OS: Micromechatronics for Biomedical Applications	649	A Novel Tool Using SMA Actuator for Cell Puncturing	Changhai Ru (Harbin Engineering Univ.), Xihua Wang (Harbin Engineering Univ.), Shuxiang Guo (Kagawa Univ.)

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1A12-5	Intelligent Systems and Control	46	A Method for Reflecting User's Intention in Interactive Multi-Objective Optimization for Multi-Satellite Communication Planning	Hiromitsu Kato (Hitachi), Shin-ichi Nakasuka (Univ. of Tokyo)
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1A14-2	OS: Observing Human	560	Proposal of a Method of Skin Region Detection by Two Near Wavelengths of Near Infrared	Taito Watanabe (Gifu Univ.), Kazuhiko Yamamoto (Gifu Univ.), Kunihito Kato (Gifu Univ.)
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1A14-4	OS: Observing Human	653	An Attempt of Applying Quality Engineering Techniques to Adjust the S/N Ratio for Measurement and Modeling of a Human Hand Shape Using High Speed Range Finder	Kengo Ohnishi (Okayama Pref. Univ.), Ryutaro Imakiire (Kyoto Seisakusho)
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1A15-2	OS: Ubiquitous Healthcare	109	The Home Health Care with the Ad-hoc Network System	Toshiyo Tamura (Chiba Univ.), Takahiro Kawada (Chiba Univ.), Masaki Sekine (Chiba Univ.)
1A15-3	OS: Ubiquitous Healthcare	336	Development of Non-invasive and Ambulatory Physiological Monitoring Systems for Ubiquitous Health Care	Shinobu Tanaka (Kanazawa Univ.), Kosuke Motoi (Kanazawa Univ.), Akira Ikarashi (Kanazawa Univ.), Masamichi Nogawa (Kanazawa Univ.), Yuji Higashi (Fujimoto Hayasuzu Hsp.), Hidetsugu Asanoi (Imizu City Hsp.), Ken-ichi Yamakoshi (Kanazawa Univ.)
1A15-4	OS: Ubiquitous Healthcare	364	Development of Real-Time Biological Data Collection System Using a Cellular Phone	David H. Hareva (Okayama Univ.), Tomoki Kitawaki (Okayama Univ.), Hisao Oka (Okayama Univ.), Takao Nakamura (Okayama Univ.), Hiroki Okada (Okayama Univ. Hsp.), Hiromi Kumon (Okayama Univ. Hsp.)
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1A17-6	Human Interface (1)	415	Laser Pointer as a Mouse	Toshiharu Wada (Shibaura Institute of Technology), Masanobu Takahashi (Shibaura Institute of Technology), Keiichiro Kagawa (NAIST), Jun Ohta (NAIST)
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1B03-5	OS: Rangefinders	248	A Ranging Approach for Speeding Up the Three-Dimensional Shape Measurement of a Specular Object	Kozo Ohtani (Hiroshima Inst. of Tech.), Mitsuru Baba (Ibaraki Univ.)
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1B05-4	Robust Control (1)	530	An Iterative Method for Output Feedback Mixed H_2/H_{∞} Control Problem	Yasushi Kami (Akashi National College of Tech.), Eitaku Nobuyama (Kyushu Institute of Tech.)
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1B07-1	Adaptive Control (1)	162	Adaptive PID Control for Perfect Tracking Problem of MIMO	Kenichi Tamura (Keio Univ.), Hiromitsu Ohmori (Keio Univ.)
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1B09-4	OS: AUN/Seed-Net Benchmark Problem on Control En	138	Robust Controller Design for a Rotary Double Inverted Pendulum using Linear Matrix Inequalities	Ha Hoang (Chulalongkorn Univ.), Manop Wongsaisuwan (Chulalongkorn Univ.)
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1B11-4	Systems and Education	200	Parameter Conditions and Least Squares Identification of Single-input Single-output Convex Fuzzy System	Tae-Wook Kim (POSTECH), Sang Y. Park (Intellix), Jin S. Lee (POSTECH)
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1B14-1	OS: Theory and Application of Histogram Frequency In	486	Current State and the Future of Image Features	Hiroyasu Koshimizu (Chukyo Univ.), Shunichiro Oe (Univ. of Tokushima)
1B14-2	OS: Theory and Application of Histogram Frequency In	618	Introduction of Frequency Image and applications	Toshiyuki Kashiwagi (Tokushima Prefectural Industrial Technology Center), Shunichiro Oe (Univ. of Tokushima)
1B14-3	OS: Theory and Application of Histogram Frequency In	631	On CFI and CFI-based Filters	Takayuki Fujiwara (Chukyo Univ.), Hiroyasu Koshimizu (Chukyo Univ.)
1B14-4	OS: Theory and Application of Histogram Frequency In	568	Visual Defects Classification System Using Co-occurrence Histogram Image	Tepppei Iga (Kagawa Univ.), Takateru Tanaka (Kagawa Univ.), Jun-ichiro Hayashi (Kagawa Univ.), Seiji Hata (Kagawa Univ.)
1B15-1	OS: Interaction and Intelligence	224	Particle Swarm Intelligence Robot Vision for Multiple Human Tracking of A Partner Robot	Indra Adjij Sulistijono (Tokyo Metropolitan Univ.), Naoyuki Kubota (Tokyo Metropolitan Univ.)
1B15-2	OS: Interaction and Intelligence	309	Information Support System with Case-Based Reasoning Using Motion Recognition in Human-Centered City	Tomo Okawa (Tokyo Metropolitan Univ.), Eri Sato (Tokyo Metropolitan Univ.), Toru Yamaguchi (Tokyo Metropolitan Univ.)

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1B15-4	OS: Interaction and Intelligence	230	Development of Muscle Suit for Supporting Manual Worker	Hiroshi Kobayashi (Tokyo Univ. of Science), Shou Hasegawa (Tokyo Univ. of Science), Hirokazu Nozaki (Tokyo Univ. of Science)
1B15-5	OS: Interaction and Intelligence	567	Pen Tablet Interface Using Surface Acoustic Wave Tactile Display	Masaya Takasaki (Saitama Univ.), HongXu Ji (Saitama Univ.), Hiroyuki Kotani (Saitama Univ.), Takeshi Mizuno (Saitama Univ.)
1B16-1	Mechatronics Systems	320	Control for Robust Standing of a Bipedal Robot by Sole Pressure	Junya Aoki (Hosei Univ.), Kajiro Watanabe (Hosei Univ.)
1B16-2	Mechatronics Systems	366	Control Strategy for the Massage Chair Based on Human Skin Elasticity	Tatsuya Teramae (Tottori Univ.), Daisuke Kushida (Tottori Univ.), Fumiaki Takemori (Tottori Univ.), Akira Kitamura (Tottori Univ.), Masashi Fujikawa (Family Co,Ltd.), Hideshi Kondo (Family Co,Ltd.)
1B16-3	Mechatronics Systems	61	Improved Performance of Sensorless Induction Motor Using Reactive Power	Jung Ho Han (Pusan National Univ.), Min Yeong Jang (Pusan National Univ.), Guen Bo Lee (Pusan National Univ.), Bong su Jang (Pusan National Univ.), Young Ahn Kwon (Pusan National Univ.)
1B16-4	Mechatronics Systems	306	Optimal Reduction Ratio Minimizing Dissipated Energy in a Servo System with Gear	Yiting Zhu (Shimane Univ.), Teruyuki Izumi (Shimane Univ.), Zuwei Li (Shimane Univ.), Hai Zhou (Shimane Univ.)
1B16-5	Mechatronics Systems	175	Development of Dynamics Modeling in the Vehicle Simulator for Road Safety Analysis	Kyung-Ho Bang (Myongji College)
1B17-1	Human Interface (2)	116	Investigation of Playing with Entertainment Robotic Pet of Pre-School Aged Child	Satoshi Yamamoto (Teikyo Univ.), Ryuhei Kimura (Teikyo Univ.)
1B17-2	Human Interface (2)	556	Estimation of Musical Pitch by Using Comb Filters for the Identification of Musical Instruments	Atsushi Todo (Kagawa Univ.), Hideyuki Sawada (Kagawa Univ.)
1B17-3	Human Interface (2)	459	Simultaneous Generation of Various Shaped Sound Spots with Multiple Linear Speaker Arrays	Kyosuke Horio (Tokyo Univ. of Science), Yuuk Ohtomo (Tokyo Univ. of Science), Hiroshi Takemura (Tokyo Univ. of Science), Hiroshi Mizoguchi (Tokyo Univ. of Science)
1B17-4	Human Interface (2)	458	Implementation of Luggable Linear Speaker Array System and Formation of Sound Spot	Yu Fukasawa (Tokyo Univ. of Science), Hiroshi Takemura (Tokyo Univ. of Science), Hiroshi Mizoguchi (Tokyo Univ. of Science)
1B17-5	Human Interface (2)	465	Computers' Synchronization for Large-Scale Loudspeaker Array System	Yuki Ohtomo (Tokyo Univ. of Science), Hiroshi Takemura (Tokyo Univ. of Science), Hiroshi Mizoguchi (Tokyo Univ. of Science)
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1C01-2	Signal Processing in Medical and Biological Engineering	392	Adaptive Wiener Filter based on Gaussian Mixture Distribution Model for Denoising Chest X-ray CT	Motohiro Tabuchi (Okayama Univ.), Nobumoto Yamane (Okayama Univ.), Yoshitaka Morikawa (Okayama Univ.)
1C01-3	Signal Processing in Medical and Biological Engineering	239	Vein Emphasis Filter for Biometric Authentication.	Shinichiro Watanabe (Keio Univ.), Toshiyuki Tanaka (Keio Univ.), Eizaburo Iwata (Universal Robot Inc)
1C01-4	Signal Processing in Medical and Biological Engineering	272	Telemedicine System of Pathology Image using the Internet.	Ayako Suzuki (Keio Univ.), Toshiyuki Tanaka (Keio Univ.)
1C01-5	Signal Processing in Medical and Biological Engineering	318	Tumor Detection Method of Small Animals on X-ray Images	Yuji Karita (Keio Univ.), Toshiyuki Tanaka (Keio Univ.), Isao Kabaya (R-Tec Corp.), Mikiya Kano (R-Tec Corp.), Isamu Iwayoshi (Japan Small Animal Medical Research Center)
1C01-6	Signal Processing in Medical and Biological Engineering	243	A Neural Network based Computer-Aided Diagnosis of Emphysema using CT Lung Images	Kok Liang Tan (Keio Univ.), Toshiyuki Tanaka (Keio Univ.), Hidetoshi Nakamura (Tokyo Electric Power Hsp.), Akitoshi Ishizaka (Keio Univ.)
1C02-1	Opto-Electronic Engineering	22	Profiler Design with Multi-Sensor Data Fusion Methods	Jium-Ming Lin (Chung-Hua Univ.), Jiea-Chie Lin (Chung-Hua Univ.)
1C02-2	Opto-Electronic Engineering	232	The Influence of Probe Geometry on Muscle Oxygenation Measurement Using Spatially-resolved NIRS	Shingo Sone (Shizuoka Univ.), Masatsugu Niwayama (Shizuoka Univ.), Shigenobu Shinohara (Shizuoka Univ.)
1C02-3	Opto-Electronic Engineering	474	Development of 3-axis Distributed Forces Sensor for Walking Analysis	Masahiro Ueda (Tokyo Univ. of Science), Harutaka Uno (Tokyo Univ. of Science), Hiroshi Takemura (Tokyo Univ. of Science), Hiroshi Mizoguchi (Tokyo Univ. of Science)

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1C02-5	Opto-Electronic Engineering	651	Voice Separation Ability and Brain Activation Measurement Based on NIRS Analysis	Di Miao (Kochi Univ. of Technology), Shuoyu Wang (Kochi Univ. of Technology)
1C03-1	OS: Visual 3-D Measurement	355	A Proposal of Quasi Multi-Baseline-Stereo Measuring Method with Single Camera for Reducing Occlusion	Takashi Watanabe (Chukyo Univ.), Akira Kusano (Chukyo Univ.), Takayuki Fujiwara (Chukyo Univ.), Hiroyasu Koshimizu (Chukyo Univ.)
1C03-2	OS: Visual 3-D Measurement	170	3D Measurement of Flexible Objects by Robust Motion Stereo	Yukiyasu Domae (Hokkaido Univ.), Hidenori Takauji (Hokkaido Univ.), Shun'ichi Kaneko (Hokkaido Univ.), Takayuki Tanaka (Hokkaido Univ.), Haruhisa Okuda (Mitsubishi Electric Corp.)
1C03-3	OS: Visual 3-D Measurement	514	A Implementation of Humanoid Vision Analysis of Eye Movement and Implementation to Robot-	Masayuki Shamoto (Gifu Univ.), Kunihito Kato (Gifu Univ.), Kazuhiko Yamamoto (Gifu Univ.)
1C03-4	OS: Visual 3-D Measurement	36	Model Reconstruction based on Radial Reach Filter	Satoru Takahashi (Kagawa Univ.), Shunichi Kaneko (Hokkaido Univ.)
1C03-5	OS: Visual 3-D Measurement	120	Robust Focusing by Orientation Code Matching	Yuan Li (Hokkaido Univ.), Isao Ohmura (Hokkaido Industrial Research Institute), Hidenori Takauji (Hokkaido Univ.), Shunichi Kaneko (Hokkaido Univ.), Takayuki Tanaka (Hokkaido Univ.)
1C03-6	OS: Visual 3-D Measurement	398	Nano-Level 3-D Measurement System Using Combination of 3-Wavelength Laser Lights	Masashi Nomura (Kagawa Univ.), Junichiro Hayashi (Kagawa Univ.), Shigeaki Morimoto (Co Ryusyosangyo), Sheiji Hata (Kagawa Univ.), Ichiro Ishimaru (Kagawa Univ.)
1C06-1	Medical and Welfare Systems	245	Omni-Directional Vision Sensor Based Behavior Monitoring System Using Bayesian Network	Hirokazu Seki (Chiba Institute of Technology), Atsushi Kiso (Chiba Institute of Technology), Susumu Tadakuma (Chiba Institute of Technology)
1C06-2	Medical and Welfare Systems	121	Measurement of Heart-beat of Train Operators	Yoshihiro Kawanishi (Hosei Univ.), Kouta Aizawa (Hosei Univ.), Kajiro Watanabe (Hosei Univ.)
1C06-3	Medical and Welfare Systems	217	Source Localization with EEG Data for BP Shows Major Activities in the Frontal Areas of the Brain	Rajkishore Prasad (UEC), Hovagiam Bakardjian (RIKEN, BSI), Cichocki Andrej (RIKEN BSI), Matsuno Fumitoshi (UEC)
1C06-4	Medical and Welfare Systems	419	Continuous Blood Pressure Measurement System Based on Low Cuff Pressure Approach	Cang-Yi Ding (National central Univ.), Cheng-Ning Huang (National central Univ.), Fang-Ming Yu (St. John's Univ.), Hung-Yuan Chung (National central Univ.)
1C06-5	Medical and Welfare Systems	63	Noninvasive Measurement of Blood Glucose Based on Optical Sensing and Internal Standard Method	Fujio Saiki (Shinshu Univ.), Hiroaki Ishizawa (Shinshu Univ.), Akinobu Muro (Shinshu Univ.), Eiji Toba (Shinshu Univ.)
1C06-6	Medical and Welfare Systems	227	3-D Reconstruction Using Color Stripe and Its Application to Grading of Facial Palsy	Junichi Sakaeda (Keio Univ.), Toshiyuki Tanaka (Keio Univ.)
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1C07-2	Process Control	511	Tuning Method of PID Controller for Desired Damping Coefficient	Yohei Okada (Toyohashi Univ. of Technology), Yuji Yamakawa (Univ. of Tokyo), Takanori Yamazaki (Oyama National College of Technology), Shigeru Kurosu (Crotech)
1C07-3	Process Control	173	Discrete Time Models of a Continuous Power System Stabilizer	Gaber Shabib Salman Ahmed (Univ. of Tsukuba), Noriyku Hori (Univ. of Tsukuba)
1C07-4	Process Control	603	Performance-Based PID Tuning and It's Experimental Evaluation	Yoshihiro Ohnishi (Kure College of Tech.), Toru Yamamoto (Hiroshima Univ.), Sirish L. Shah (Univ. of Alberta)
1C07-5	Process Control	53	Optimum Quality Design Support System for Steel Products using Locally-Weighted Regression Model	Hiroyasu Shigemori (JFE Steel Corp.), Shuji Kawamura (JFE Steel Corp.)
1C07-6	Process Control	555	Robust Model Predictive Control for Uncertain State Delayed System Using Polytope Dependent Lyapunov Function	Daehyun Ji (POSTECH), Woojong Yoo (POSTECH), Sangsu Yeh (POSTECH), Sanchul Won (POSTECH)
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1C08-3	OS: Medical Care and Welfare Engineering as a Man-	476	A Study of Powered Wheelchair Operation	Masayuki Booka (Hiroshima Internatinal Univ.), Osamu Sueda (Univ. of Tokushima), Shoichiro Fujisawa (Univ. of Tokushima)
1C08-4	OS: Medical Care and Welfare Engineering as a Man-	489	The Dynamically Analyzed About a Body Load of a Caregiver with Supine to Long Sitting	Masayuki Soma (Aomorzikeikai Hsp.), Shoichiro Fujisawa (Univ. of Tokushima), Osamu Sueda (Univ. of Tokushima)
1C08-5	OS: Medical Care and Welfare Engineering as a Man-	493	A New System to Measure Color Conspicuity: To Know What Color is Vivid to People with Low Visual Capacity	Seiji Mitani (National Institute of Technology and Evaluation), Toshiaki Yoshida (National Institute of Technology and Evaluation), Kouki Terada (Univ. of Tokushima), Shoichiro Fujisawa (Univ. of Tokushima), Osamu Sueda (Univ. of Tokushima)
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1C09-4	OS: Recent Advances in Distributed Parameter System	450	Passivity of Flexible Master-Slave Manipulator	Hiroyuki Ukai (Nagoya Institute of Technology), Yoshifumi Morita (Nagoya Institute of Technology), Takahito Mori (Gifu National College of Technology)
1C09-5	OS: Recent Advances in Distributed Parameter System	263	Tip Position Control of a Two Links Flexible Manipulator Based on the Dynamic Extension Technique	Toshimi Shimizu (Niigata Univ.), Minoru Sasaki (Gifu Univ.), Tokuji Okada (Niigata Univ.)
1C09-6	OS: Recent Advances in Distributed Parameter System	463	Stabilized Controller Design for a Flexible Stacker Crane	Minoru Sasaki (Gifu Univ.), Toshimi Shimizu (Niigata Univ.), Koji Ikai (Gifu Univ.), Satoshi Ito (Gifu Univ.)
1C09-7	OS: Recent Advances in Distributed Parameter System	126	A Finite-dimensional Uncertainty Modeling for Parabolic Distributed Parameter Systems	Jun Imai (Okayama Univ.)
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1C10-2	OS: Unconventional Computation and Communication	321	Multistate Part for Mesoscale Self-Assembly	Daiko Tsutsumi (Tokyo Institute of Technology), Satoshi Murata (Tokyo Institute of Technology)
1C10-3	OS: Unconventional Computation and Communication	332	Computation by Wave Propagation Simulated on Self-Timed Cellular Automaton	Tomoyuki Hisamori (Univ. of Hyogo), Teijiro Isokawa (Univ. of Hyogo), Ferdinand Peper (NiCT), Naotake Kamiura (Univ. of Hyogo), Nobuyuki Matsui (Univ. of Hyogo)
1C10-4	OS: Unconventional Computation and Communication	469	Morphological Dynamics in a Proto-cell Model	Keisuke Suzuki (Univ. of Tokyo), Takashi Ikegami (Univ. of Tokyo)
1C10-5	OS: Unconventional Computation and Communication	479	On Information-Theoretical Formalization of Intracellular Communications Based on Linear Network Coding	Jian-Qin Liu (NICT)
1C11-1	OS: System Analysis and Intelligent Design of Multiple	508	Object Location Prediction Based on Motion Estimation and Traffic Density on Digital Video	Feng-Li Lian (National Taiwan Univ.), Ching-Chun Chiang (National Taiwan Univ.)
1C11-2	OS: System Analysis and Intelligent Design of Multiple	529	Actuation Design of 2D Rotational Modular Robots	Ming-Chiuan Shiu (National Taiwan Univ.), Hou-Tsan Lee (National Taiwan Univ.), Feng-Li Lian (National Taiwan Univ.), Li-Chen Fu (National Taiwan Univ.)
1C11-3	OS: System Analysis and Intelligent Design of Multiple	531	Development of a Patrol Robot for Home Security with Network Assisted Interactions	Jong-Hann Jean (St. John's Univ.)
1C11-4	OS: System Analysis and Intelligent Design of Multiple	538	The Time-Delay Effect of Multiple-Network Systems in NCS	Ching-Wen Cheng (National Chiao-Tung Univ.), Chien-Liang Lai (National Chiao-Tung Univ.), Bor-Chyun Wang (China Univ. of Technology), Pau-Lo Hsu (National Chiao-Tung Univ.)
1C11-5	OS: System Analysis and Intelligent Design of Multiple	536	LMI-Based Fuzzy Stabilization for Multiple Networked Systems	Kuang-Yow Lian (Chung-Yuan Christian Univ. and National Taipei Univ. of Technology), Wen-Tsung Yang (Chung-Yuan Christian Univ.), Yu-Jyun Huang (Chung-Yuan Christian Univ.)
1C11-6	OS: System Analysis and Intelligent Design of Multiple	527	A Matrix Approach for Determining Linear Time-Delay System Stability for All Time-Delay Sizes	Chun Pi Lin (National Taiwan Univ.), I Kong Fong (National Taiwan Univ.)
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1C12-3	Systems Theory and Engineering	432	Some Algorithms for Real-Time Generation of Non-Regular Sequences on One-Bit Inter-Cell-Communication Cellular Automata	Naoki Kamikawa (Osaka Electro-Communication Univ.), Hiroshi Umeo (Osaka Electro-Communication Univ.)
1C12-4	Systems Theory and Engineering	191	Proposal of Web System "NAP-Web" to Promise Next Access	Tomohiko Kaji (Kagawa Univ.), Keizo Saisho (Kagawa Univ.)
1C12-5	Systems Theory and Engineering	549	Development of PANGEA and SICE Academic Activity Support Systems	Takao Terano (Tokyo Institute of Technology), Yukichi Otsuka (Gakkai Net Co., Ltd.), Masashi Kugawa (Gakkai Net Co., Ltd.), Setsuya Kurahashi (Univ. of Tsukuba)
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1C13-2	Neural Networks and their Application	291	Control of Roving Robot Using Chaotic Dynamics in A Quasi-layered Recurrent Neural Network for Sensing and Driving	Li Yongtao (Okayama Univ.), Tai Tanaka (Okayama Univ.), Shigetoshi Nara (Okayama Univ.)
1C13-3	Neural Networks and their Application	3	Sliding Mode Control Using Neural Networks for SISO Nonlinear Systems	Muhammad Yasser (Chiba Univ.), Agus Trisanto (Chiba Univ.), Ayman Haggag (Chiba Univ.), Takashi Yahagi (Chiba Univ.), Hiroo Sekiya (Chiba Univ.), Jianming Lu (Chiba Univ.)
1C13-4	Neural Networks and their Application	183	Characteristic of Adaptive Type Neural Network Direct Controller with Separate Learning Rule	Takayuki Yamada (Ibaraki Univ.)
1C13-5	Neural Networks and their Application	424	Inverse Estimation of Joint Angles of Robot Arm by Network Inversion	Nanae Sekiguchi (Takushoku Univ.), Takehiko Ogawa (Takushoku Univ.), Hajime Kanada (Takushoku Univ.)
1C13-6	Neural Networks and their Application	581	Implicit estimation of other's intention without direct observation of actions in a collaborative task: Situation-Sensitive Reinforcement Learning	Tadahiro Taniguchi (Kyoto Univ.), Kenji Ogawa (Kyoto Univ.), Tetsuo Sawaragi (Kyoto Univ.)
1C14-1	OS: Biomimetic Approach in Robotics and Machines	72	Task Allocation with a Cooperative Plan for an Emotionally Intelligent System of Multi-Robots	Sajal C. Banik (Saga Univ.), Keigo Watanabe (Saga Univ.), Kiyotaka Izumi (Saga Univ.)
1C14-2	OS: Biomimetic Approach in Robotics and Machines	210	Multi-Preview Configuration Control for Redundant Manipulator by Future Reachability Evaluation	Zhang Tongxiao (Univ. of Fukui), Minami Mamoru (Univ. of Fukui), Song Wei (Univ. of Fukui)
1C14-3	OS: Biomimetic Approach in Robotics and Machines	390	CPG Based Control for Generating Stable Bipedal Trajectories Under External Perturbation	Guang Lei Liu (Saga Univ.), Maki K. Habib (Saga Univ.), Keigo Watanabe (Saga Univ.), Kiyotaka Izumi (Saga Univ.)
1C14-4	OS: Biomimetic Approach in Robotics and Machines	457	On-line Stable Evolutionary Recognition by Quaternion Motion-Feedforward Compensation	Wei Song (Univ. of Fukui), Mamoru Minami (Univ. of Fukui), Yasushi Mae (Univ. of Fukui), Seiji Aoyagi (Kansai Univ.)
1C14-5	OS: Biomimetic Approach in Robotics and Machines	636	Learning of Inverse-dynamics and Inverse-kinematics for Two-link SCARA Robot Using Neural Networks	Ken Onozato (Kansai Univ.), Yutaka Maeda (Kansai Univ.)
1C14-6	OS: Biomimetic Approach in Robotics and Machines	637	Hardware Design of Self-Organization for Clustering	Atsushi Ishihara (Kansai Univ.), Yutaka Maeda (Kansai Univ.)
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1C16-2	Robot Control (2)	142	A Controller Design on Person Following Omni-directional Vehicle Robots	Prasarn Kiddee (Polytechnic Univ.), Akira Shimada (Polytechnic Univ.)
1C16-3	Robot Control (2)	297	Development of Autonomous Bike Robot with Balancer	Akihiro Murayama (Mechanical and Control Eng Tokyo Institut of Technology), Masaki Yamakita (Mechanical and Control Eng Tokyo Institut of Technology)
1C16-4	Robot Control (2)	657	Obstacle avoidance, arrest and guidance of a prismatic 2D object using multi agents	Ashish Dutta (IIT Kanpur), Pankaj Sharma (IIT Kanpur), Anupam Saxena (IIT Kanpur)
1C16-5	Robot Control (2)	667	Development of Walking Assist Equipment with Pneumatic Cylinder	Toshihiko Morichika (Meiji Univ.), Fumitaka Kikkawa (Meiji Univ.), Osamu Oyama (Meiji Univ.), Toshihiro Yoshimitsu (Kanagawa Institute of Technology)
1C17-1	Robot Arm and Manipulator	425	A Method of Real-time Coordination of Redundant Muscles for Multi-DOF Robot Joints	Masakazu Suzuki (Tokai Univ.), Takashi Mayahara (Tokai Univ.)
1C17-2	Robot Arm and Manipulator	483	Multiple Obstacles Avoidance for Kinematically Redundant Manipulators Using Jacobian Transpose Method	Kwang-Kyu Lee (Technical Univ. Munich), Yuta Komoguchi (Technical Univ. Munich), Marin Buss (Technical Univ. Munich)
1C17-3	Robot Arm and Manipulator	655	Motion Simulation of Robot Arm Using Reinforcement Learning	Oshiro Takahito (Hosei Univ.), Watanabe Kajiro (Hosei Univ.)
1C17-4	Robot Arm and Manipulator	518	Regenerating Human-like Arm Motions of Humanoid Robots for a Movable Object	ChangHwan Kim (KIST), Seungsu Kim (KIST), Syungkwon Ra (KIST), Bum Jae You (KIST)

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2A01-2	Neural Networks	329	Impact Perforation Image Processing using a Self-Organizing Map	Kenji Okubo (Takushoku Univ.), Takehiko Ogawa (Takushoku Univ.), Hajime Kanada (Takushoku Univ.)
2A01-3	Neural Networks	335	A BER Worst Pattern of Waveform Discrimination Using 2-7 Code Neural Networks	Kouta Miyazato (Takushoku Univ.), Takehiko Ogawa (Takushoku Univ.), Hajime Kanada (Takushoku Univ.), Shigeru Yoshizawa (Takushoku Univ.)
2A01-4	Neural Networks	350	EMG Pattern Classification using Spectral Estimation and Neural Network	Kyung Kwon Jung (Dongguk Univ.), Joo Woong Kim (Dongguk Univ.), Ki Hwan Eom (Dongguk Univ.), Hyun Kwan Lee (Honam Univ.), Sung Boo Chung (Seoil College)
2A01-5	Neural Networks	251	Medical Image Recognition of Abdominal X-ray CT Images by RBFGMDH-type Neural Network	Tadashi Kondo (Univ. of Tokushima), Junji Ueno (Univ. of Tokushima)
2A01-6	Neural Networks	280	Three Dimensional Medical Images of the Lungs and Brain Recognized by Artificial Neural Networks	Takaomi Matuki (Univ. of Tokushima), Tsuyoshi Kudo (Univ. of Tokushima), Tadashi Kondo (Univ. of Tokushima), Junji Ueno (Univ. of Tokushima)
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2A02-2	OS: Human Factors in Vehicle Operation	70	Effect of Safe-driving Instructions on Driver Behavior at Non-signalized Intersection	Hiroaki Kosaka (NAIST), Nobuhisa Higashikawa (NAIST), Hirokazu Nishitani (NAIST)
2A02-3	OS: Human Factors in Vehicle Operation	339	Indices for Characterizing Driving Style and their Relevance to Car Following Behavior	Motonori Ishibashi (Mazda Motor Corp.), Masayuki Okuwa (Toyota Central RandD Labs. Inc.), Shun'ichi Doi (Kagawa Univ.), Motoyuki Akamatsu
2A02-4	OS: Human Factors in Vehicle Operation	487	Modeling and Validation of Carsickness Mechanism	Norimasa Kamiji (Kagawa Univ.), Yoshinori Kurata (Kagawa Univ.), Takahiro Wada (Kagawa Univ.), Shun'ichi Doi (Kagawa Univ.)
2A02-5	OS: Human Factors in Vehicle Operation	623	Characteristic of Depth Attention when Observer is in Dark Field	Ruting Xia (Kagawa Univ.), Masato Fukushima (Kagawa Univ.), Shun'ichi Doi (Kagawa Univ.), Takahiko Kimura (Osaka Univ.), Toshiaki Miura (Osaka Univ.)
2A03-1	OS: Evolutionary and Distributed Systems Towards Real-time	448	Waterbus Route Optimization by Pittsburgh-style Learning Classifier System	Keiji Sato (Univ. of Electro-Communications), Keiki Takadama (Univ. of Electro-Communications)
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