

MA2-17-3 Optimal Pump and Inverter Control for Drinking Water and Wastewater Treatment Systems

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Water flow rate control of the multiple inverter controlled pumps



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2. Problem formulation



Consider the following optimization problem.

$\min\{c(x):x\in\mathfrak{R}^n\}$

 $\cdot C(x)$ is assumed to be a bounded smooth function Global minimal solution exists and the number of local minimal solutions are finite.

Our approach for searching multiple local optimal solutions : We transform the optimization problems into nonlinear dynamics and solve the problem.

Optimization Problems and Nonlinear Dynamics

Optimization Problems	⇔	Nonlinear Dynamics
Objective function	⇔	Vector field
Local optimal solution	⇔	Stable equilibrium point (S
Global optimal solution	⇔	Stable equilibrium poin
Saddle points on the ridge of the objective function	⇔	Decomposition point,Type I u equilibrium point (UEP)
Convergence region	⇔	Stability Region
Boundary of the convergence region	⇔	Stability Boundary

Find multiple stable equilibrium points ⇒Find multiple local optimal solutions





3. The concept of the optimization for searching optimal solutions



Initial value

The concept has been proposed by Prof. Chiang at Cornell in 1996.

Find multiple local optimal solutions.

Significant two search steps:

STEP1

A local search from a white point (or an initial point) to a black point.

 $\bigcirc \Rightarrow \bigcirc$

STEP2:

A global search from a black point to a white point. $\bullet \Rightarrow \bigcirc$



This method can search a solution for energy savings.



2-STEP for finding multiple local optimal solutions





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4. The previous method for searching decomposition poin 5 e-Front runners

This method has been proposed by Chiang in 1996.



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5. The proposed method for searching decomposition points



Parameter dependence of the vector field (Bifurcation)



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Bifurcation Diagram



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6. A numerical example for inverter controlled pumps



Minimize:
$$P_{v} = \sum_{i=1}^{N} \frac{\gamma_{3i} x_{i}^{3} + \gamma_{1i} x_{i}}{\alpha_{2i} x_{i}^{2} + \alpha_{0i} + x_{i} \sqrt{\beta_{4i} x_{i}^{2} + \beta_{2i}}}$$

Subject to:
$$\begin{cases} Q_{T} = \sum_{i=1}^{N} x_{i} \\ x_{i} \ge 0 \end{cases}$$

 P_v :pump energy x_1 :ith pump water flow rate Q_T :total pump water flow rate The others: pump constants

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Constants (standard):

The number of the pumps: N=2 Rated pump water flow rate $Q_0 total = 11196[m^3/h]$ Rated water head H_0 total = 14[m] Actual water head $h_a = 10.47$ [m] Constant of the pipe resistance h_r=10.67[m] Each pump water flow rate Q_{total}=4608[m³/h] $(Q_{pu_total_total}^{i}=0.4116[pu])$ Motor efficiency $\eta_{m_i}=94[\%](i=1,2)$ Inverter efficiency $\eta_{i}^{-}=97[\%](i=1,2)$

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No.	Water flow rate	Pump energy	Remarks
Optimal solution 1	No.1 pump:2367[m ³ /h] (0.2113pu) No.2 pump:2241[m ³ /h] (0.2001pu) Total water flow rate: 4608[m ³ /h]	213.8[kW] (100%)	No.1 pump: running No.2 pump: running
Optimal solution 2	No.1 pump: 0.0[m³/h] No.2 pump: 4608[m³/h] (0.4114pu) Total water flow rate: 4608[m³/h]	179.7[kW] (84.05%)	No.1 pump: shutdown No.2 pump: running
Optimal solution 3	No.1 Pump: 4608[m ³ /h] (0.4114pu) No.2 pump: 0.0[m ³ /h] Total water flow rate: 4608[m ³ /h]	170.5[kW] (79.75%)	No.1 pump: running No.2 pump: shutdown
Pump energy	Non-convex Optimal solution 1 O timal ution	ptimal olution 3	e usually select optim ution 3. We also sele ner optimal solutions.

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7. Concluding remarks



The paper presented the systematic optimization method based on topological and geometric properties of the objective function for obtaining multiple local optimal solutions of the inverter controlled pumps.

The proposed method has ability to search multiple local optimal solutions systematically and guarantees at least local optimality of the obtained solutions mathematically.

For the purpose of illustrating the proposed method, the inverter controlled twopump system is studied numerically. The three local optimal solutions are obtained, and one of the obtained solutions leads the lowest energy.

The numerical results have shown the effectiveness of the proposed method.

Application to the practical drinking water and wastewater treatment systems is the future work.

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