

SICE Annual Conference 2008 Session Table (August 22 (FRI))

	Room01	Room02	Room03	Room04	Room05	Room06	Room07	Room08	
9:00	3A01 Mass and Force Sensing	3A02 Identification and Estimation	3A03 Education and Design Support Sysmtems	3A04 Devices & Human Interfaces	3A05 Biological and Physiological Engineering (1)	3A06 Safety and Eco Systems	3A07 Manipulator Control	3A08 Human Interfaces - Man/Machine	9:00
11:00									11:00
11:15 12:15	Plenary Talk / Auditorium "The Psychology of Human-Robot Interaction"				Prof. John Baillieul (Boston Univ., USA)				11:15 12:15
13:15	3B01 Ultra-High Precision Measurement	3B02	3B03 Fuzzy Systems	3B04	3B05 Biological and Physiological Engineering (2)	3B06 Vision Systems	3B07 Dynamic Walking	3B08 Entertainment Systems	13:15
15:15									15:15
	Room09	Room10	Room11	Room12	Room13	Room14	Room15	Room16	
9:00	3A09 Control for Robotic Systems	3A10 Networks, Communications and Bilateral Teleoperation	3A11 System Modeling	3A12	3A13 OS: Intelligent Control Applications	3A14 OS: Intelligent Methods for Autonomous Mobile Robots	3A15 OS: FLUCOME-J 2008		9:00
11:00									11:00
11:15 12:15	Plenary Talk / Auditorium "The Psychology of Human-Robot Interaction"				Prof. John Baillieul (Boston Univ., USA)				11:15 12:15
13:15	3B09 Control of Robotic Arms and Cranes	3B10 Nonlinear Systems	3B11 System Theory	3B12	3B13 OS: SICE City	3B14 OS: Integration in Robotics	3B15 OS: Networked Sensing Systems		13:15
15:15									15:15
	Room17	Room18	Room19	Room20	Room21	Room B-202			
9:00	3A17 OS: Advanced Robot Sensing and Control	3A18 OS: Industrial Application 1	3A19 OS: Redundant/Underactuated Robot Systems	3A20 OS: Medical Image Processing	3A21 OS: Multi-Resolved Dynamical System (MRDS)				9:00
11:00									11:00
11:15 12:15	Plenary Talk / Auditorium "The Psychology of Human-Robot Interaction"				Prof. John Baillieul (Boston Univ., USA)				11:15 12:15
13:15	3B17 OS: Statistical Mechanics	3B18 OS: Industrial Application 2	3B19 OS: Optimization and Its Applications	3B20 OS: GPS and Its Application	3B21 OS: Kukanchi: Interactive Human-Space Design and Intelligence	Invited Speech 1 (13:15-14:15) "Telehaptics" Prof. Kouhei Ohnishi (Keio Univ., Japan)			13:15
15:15						Invited Speech 2 (14:15-15:15) "Assistance Systems for the Control of Rovers" Prof. Klaus Schilling (Univ. Wuerzburg, Germany)			15:15
15:30 16:30	Closing Celemony / Auditorium								15:30 16:30
16:30 17:30	Farewell Party								16:30 17:30